

# Evolutionary Computation

2022/23

Master Artificial Intelligence

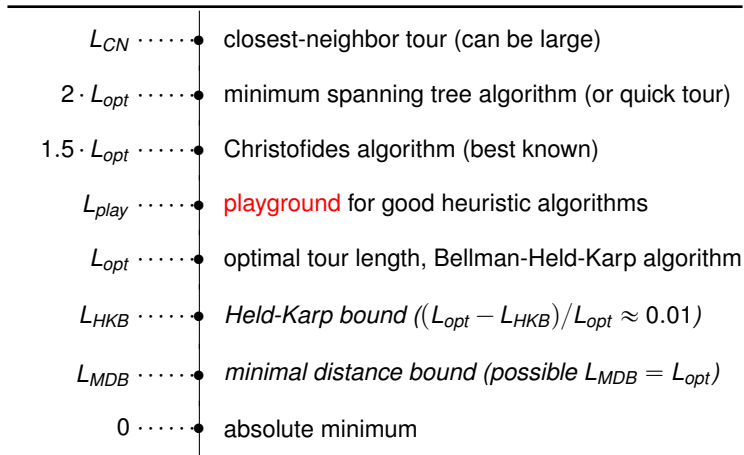
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22/23

# the TSP length-line sum-up

length of tour



additional information and benchmark instances can be found at:

- <http://comopt.ifi.uni-heidelberg.de/software/TSPLIB95/>
- almost a counterexample of how to implement GA for TSP  
<https://jaketae.github.io/study/genetic-algorithm/>
- we use the work at  
<https://github.com/guofei9987/scikit-opt>

- **Sorting is a basic**, well known, and well studied problem.
- Given a sequence of  $n$  elements belonging to an orderable set, we have to compute a permutation of the input elements such that they are ordered (according to the underlying compare function).
- Simple example: given a sequence of integer numbers; sort ascending.
- Note that there are  $n!$  possible permutations.  
(Funny, the same number as there are tours in TSP.)

- Before doing the actual sorting, let's first design an algorithm that **checks the results**, i.e., checks that the sequence is sorted.
- Remember: we require that we can check with an algorithm that the output/result of our initial algorithm is correct (i.e., fulfills the corresponding properties).
- Personally, I recommend that you **always** try to design and implement such a checker!

# checker for the sorting problem

Check whether a pair of elements is sorted:

```
def PairIsSorted(v, i, j):  
    return v[i] <= v[j]
```

Check whether a sequence of elements is sorted:

```
def IsSorted(v):  
    for i in range(len(v)-1):  
        if not PairIsSorted(v, i, i+1):  
            return False  
    return True
```

# the bubble sort algorithm

A **simple sorting** algorithm:

```
def BubbleSort (v) :  
    while not IsSorted(v) :  
        for i in range(len(v)-1) :  
            PairSort (v, i, i+1)
```

Runs in quadratic time (worst case) and linear time (best case).

# Monte Carlo sorting

Let us implement a **Monte Carlo sorting** algorithm:  
we select a random pair of elements and interchange when necessary:

```
def MonteCarloSort (v, rounds) :  
    for j in range (rounds) :  
        i, j=RandomPair (v)  
        PairSort (v, i, j)
```

Whenever the number of rounds is sufficiently large and we are lucky the sequence will become sorted.



# Las Vegas sorting

Let us implement a **Las Vegas sorting** algorithm: we select a random pair of elements, interchange when necessary, and stop when the sequence is sorted:

```
def LasVegasSort (v) :  
    while not IsSorted (v) :  
        i, j=RandomPair (v)  
        PairSort (v, i, j)
```

Maybe we need to wait a lot of time, but we always get a sorted sequence. Observe: Las Vegas algorithms are easy to design, when we have a checker!

Whenever we have a checker, we can implement a Las Vegas algorithm on the base of a Monte Carlo algorithm, so for sorting we can do:

```
def LasVegasMonteCarloSort (v, rounds) :  
    while not IsSorted(v) :  
        MonteCarloSort (v, rounds)
```

# Monte Carlo sort with Las Vegas condition

We can improve the Monte Carlo sort introducing a Las Vegas condition to stop earlier:

```
def MonteCarloLasVegasSort (v, rounds) :  
    while not IsSorted(v) and rounds>0:  
        i, j=RandomPair (v)  
        PairSort (v, i, j)  
        rounds-=1
```

This idea reflects the **general structure of a heuristic** probabilistic algorithm: for a certain time do something maybe useful, and stop when a certain condition is met.

# Efficient sorting

An **efficient**  $O(n \log n)$  algorithm is the merge sort algorithm, here written in its iterative form (divide and conquer paradigm):

```
def Merge(v, w, left, middle, right):
    i, j = left, middle
    for k in range(left, right):
        if j >= right or (i < middle and PairIsSorted(v, i, j)):
            w[k] = v[i]; i += 1
        else:
            w[k] = v[j]; j += 1

def MergeSort(w):
    s, n = 1, len(w)
    while s < n:
        v = w[:]
        for left in range(0, n, 2*s):
            Merge(v, w, left, left+s, min(left+2*s, n))
        s *= 2
```



# sorting as an optimization problem

- In order to state the integer **sorting** problem as an **optimization** problem, we need to specify an objective function.
- Let  $x = (x_1, x_2, \dots, x_n)$  be the current sequence of integer values.
- We use  $f(x) = \sum_{i=1}^n i \cdot x_i$  as objective function.
- Our aim is to maximize  $f(x)$  at which point the sequence  $x$  is sorted; to minimize we take the negative value:

```
def SortObjective(v):  
    f=0  
    for i in range(len(v)):  
        f+=v[i]*(i+1)  
    return -f
```

or

```
def SortObjective(v):  
    return -sum([v[i]*(i+1) for i in range(len(v))])
```



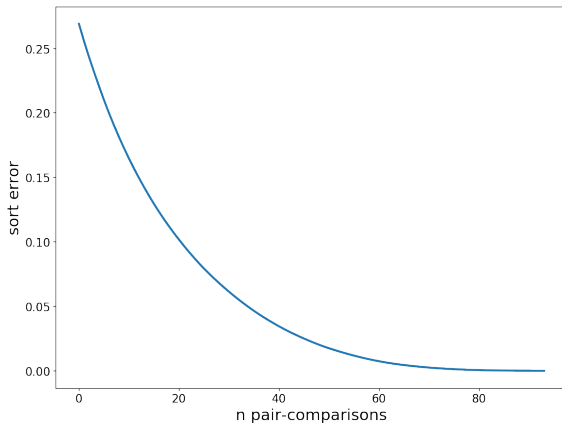
## sorting as an optimization problem

Now, we can use a **genetic algorithm** for the TSP problem to sort our sequence (note, we want an order on the cities, but now with our objective function for sorting and not the one for a minimal tour length).

```
def GASort (w) :
    ga=GA_TSP (
        func=fobj, n_dim=len(w), size_pop=100,
        max_iter=1000, probab_mut=1
    )
    best_points, best_val=ga.run()
    v=w.copy()
    for i in range(len(best_points)) :
        w[i]=v[int(best_points[i])]
```

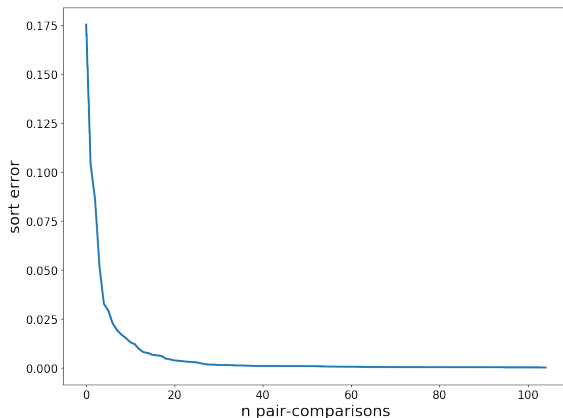
More in lab hours (fobj will be computed on a different data structure).

# convergence of bubble sort



Slow improvement, finds the minimum always.

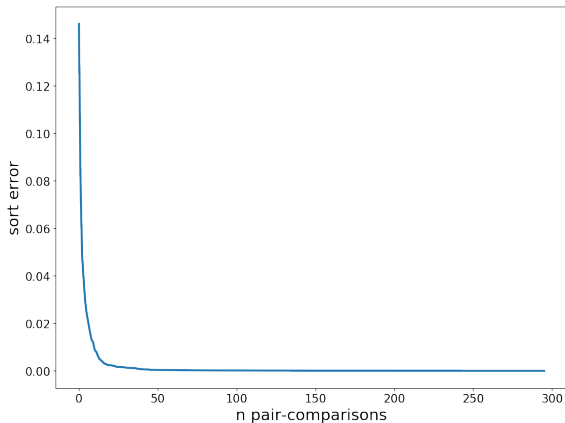
## convergence of Monte Carlo sort



Fast improvement, fixed number of steps, might **not find** minimum.

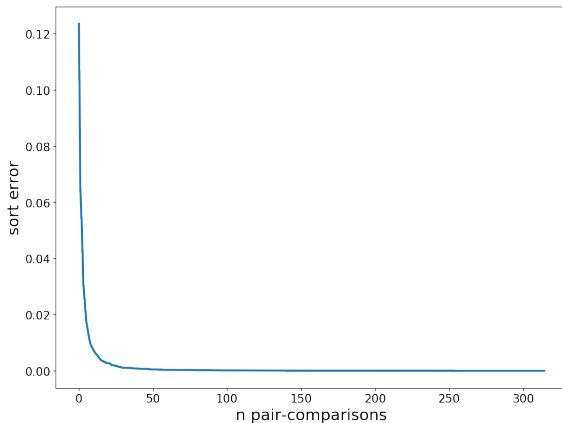


## convergence of Las Vegas sort

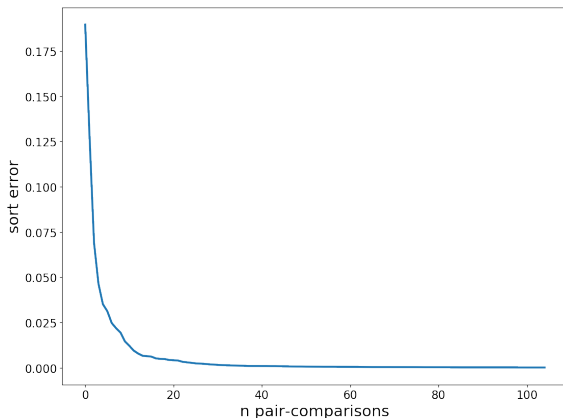


Fast improvement at the beginning, and slowly finds the minimum.

# convergence of Las Vegas with Monte Carlo sort

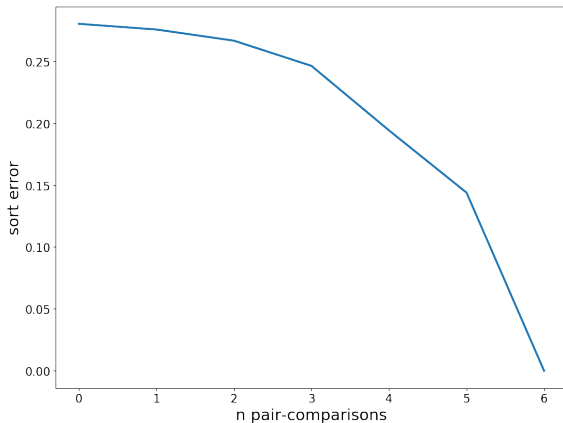


## convergence of Monte Carlo sort with Las Vegas condition



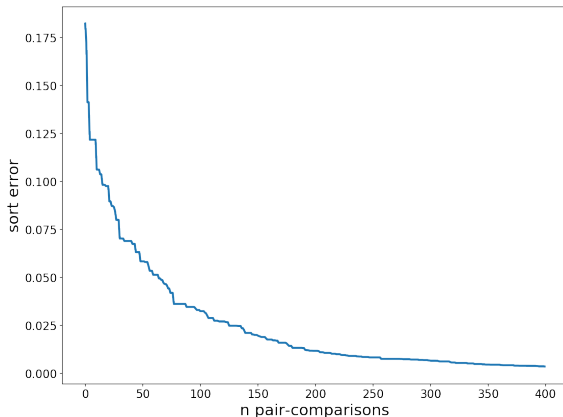
Fast improvement, but might **not find** minimum (however, stops if found).

# convergence of merge sort



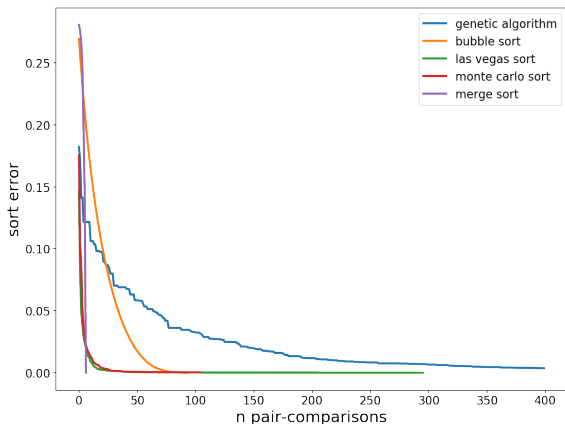
Deterministic very fast improvement, finds the minimum always!

# convergence of genetic algorithm sort



Well, works, but might **not find** the minimum.

# summary of *convergence* for sorting algorithms



Maybe the genetic algorithm is not the right choice,  
better stick to the deterministic classic one.

# Can we sort faster?

You can always ask: can we sort **faster**?

- It depends... when we have more information about the data, maybe we can sort faster!
- In the given example, we started with a random permutation of  $n$  consecutive numbers.
- So sorting them is easy: just count—starting at the minimum—up to  $n$ , hence, a linear time algorithm!
- It's always **worthwhile to analyse** the underlying data!

**Don't get betrayed** by a small number of program runs that might even *suggest* some good results (both in precision as well as in runtime). You should always ask to see several/many runs, and to determine the variance of the results, so that you can compute the **Monte Carlo standard error**.



# The (0,1)-knapsack problem

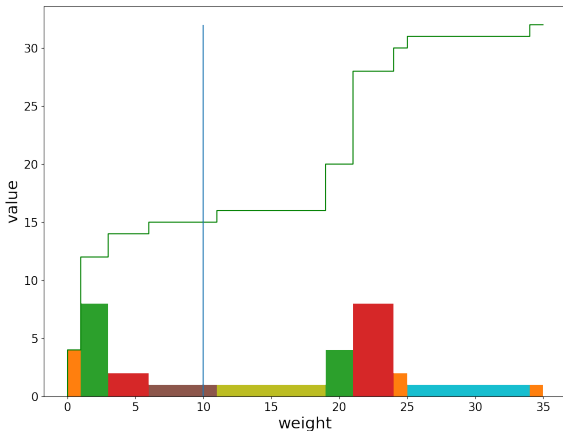
The (0,1)-knapsack problem (KSP) is another classical **combinatorial optimization** problem, where

- Given a set of items, each with a certain weight and value, and
- given a knapsack with a certain weight capacity,
- find the maximum total value you can carry with the knapsack.

Note that in this problem (in comparison to TSP or sorting) we have **infeasible** combinations (i.e., the subset might be too heavy).

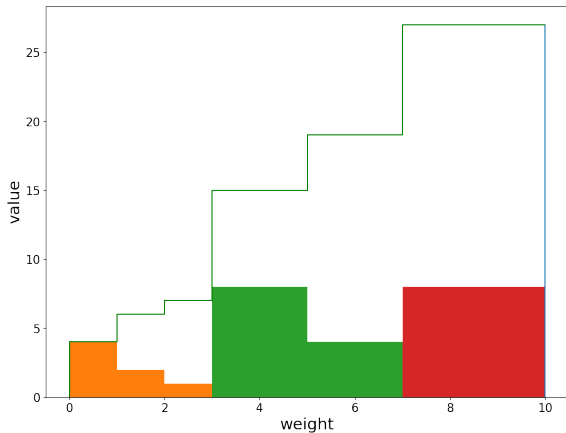
# an example knapsack problem

If we take all available items:



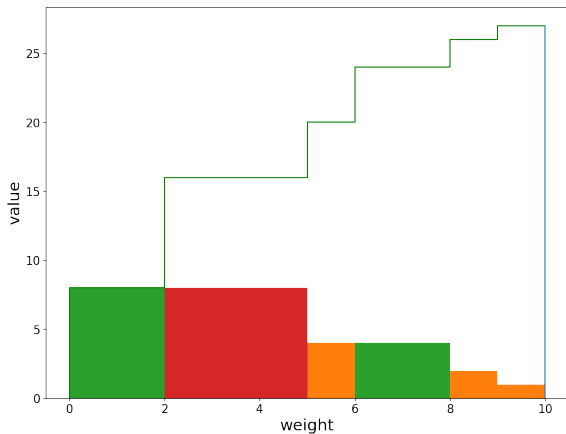
# packing the knapsack with greedy weight algorithm

We take the **lightest** items as long as they fit:



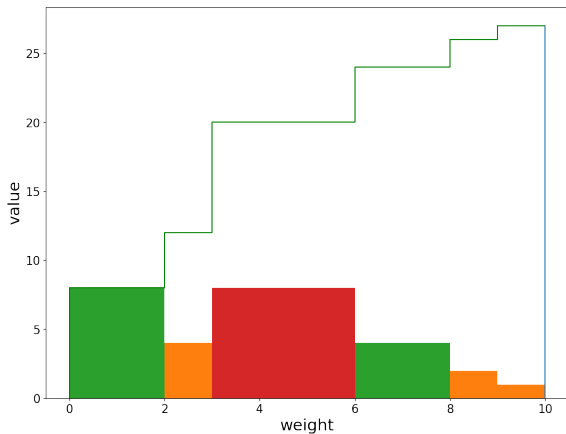
# packing the knapsack with greedy value algorithm

We take the **most valued** items as long as they fit:



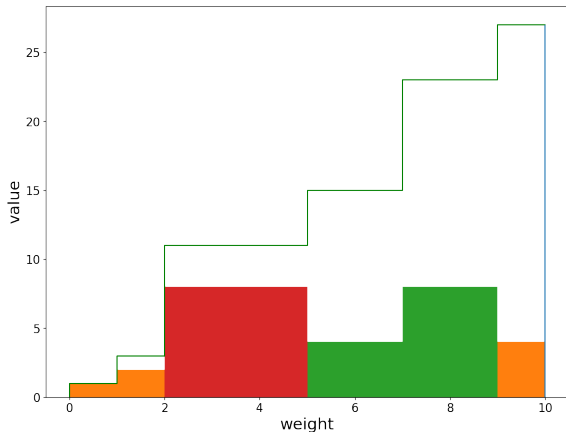
# packing the knapsack with greedy ratio algorithm

We take the **best rated** (value per weight unit) items as long as they fit:



# optimal packing the knapsack with dynamic programming

We find the **optimal** solution with dynamic programming:



# It seems all algorithms are great?

The previous algorithms all packed a value of 27 into the knapsack...

- You noticed that I have cheated?
- All algorithms found an optimal packaging!
- You know why?
- I was **lucky**.

- Monte Carlo algorithms, and hence, evolutionary algorithms are often **quite easy to parallelize**.
- We will not talk about parallelization in this course, however, it's an important issue in order to achieve performance on modern systems.



- Evolutionary methods work with **populations** of individuals (or only one individual and a certain type of memory).
- There are probabilistic **modification processes** (mutation, reproduction, recombination/crossover) that change the population from one to the next generation.
- The **performance** of the individuals is based on a **fitness** which usually is the objective function (but not necessarily).
- There is a **selection process** to maintain a (more or less) stable state (size) of the population.
- Most of the algorithmic decisions are drawn **probabilistically**.

I will not give details on the history and researchers, please, take a look at the literature/bibliography.

# Genetic algorithms (GA)

- We distinguish the **genotype** (codification of the individuals) and the **phenotype** (elements of the search space).
- There must exist a **bijection** between genotype and phenotype.
- The genotype encodes the **free parameters** of an individual.
- The modifications (mutation and recombination/crossover) are carried out over the genotype.
- The fitness is evaluated over the phenotype (our objective function).
- We have to explain: codification (of the genotype), initialization, mutation, recombination/crossover, selection, and stopping.

A genetic algorithm can be summarized in the following principal loop:

```
InitializePopulation()      # initialization
EvaluateIndividuals()      # evaluation
while not Stopping():      # stopping
    DetermineParents()      # selection
    GenerateChildren()      # recombination
    MutateChildren()        # mutation
    EvaluateIndividuals()   # evaluation
    ReestablishPopulation() # selection
```

# GA: encoding of the individuals

There are many possibilities how to **encode** the free parameters of an individual to form its genotype:

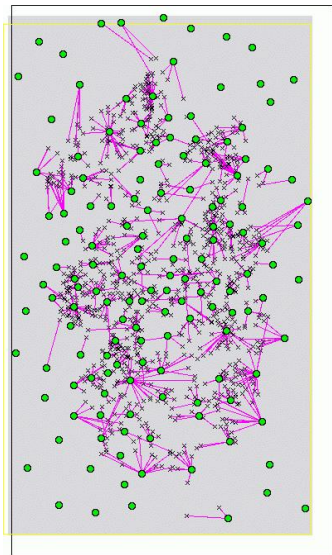
- use a binary bitstring, e.g., (101101)
- use a sequence of integer values in certain ranges, e.g.,  
(2, 6, 98, 3)  $\in [1 : 2] \times [1 : 10] \times [0 : 100] \times [1 : 5]$
- use a sequence of real values in certain ranges, e.g.,  
(1.23, 34.4, -2.1)  $\in [-50.0, 50.0]$
- use a permutation
- use a k-dimensional structure
- use a binary tree
- use a general graph
- use whatever you like (remember: do something, be happy...)

**Remember:** we need a bijection between genotype and phenotype and we need to implement crossovers and mutations that are able to explore the entire search space (or at least the region of interest).



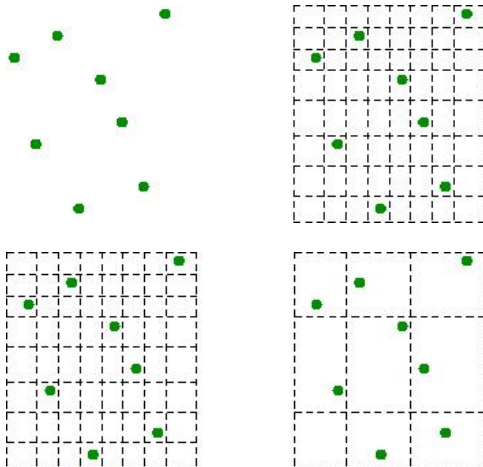
- The individual components of the sequences are called **genes**.
- The possible values of a gene are called **allele**.
- The encoding of an individual is called its **genome** or **chromosome**.

# GA: genotype an example



- green: base stations
- crosses: mobile users
- magenta: assignment
- **goal**: find the minimal subset of base stations that guarantees an assignment of all mobiles
- Note: computation of the objective function is quite complex (and will not be detailed here).

# GA: genotype an example



- initial  
8 × 8 grid
- reduced to  
3 × 3 grid
- 4 allele  
(2-bit strings)
  - unusable
  - used
  - unused
  - fixed

gene mutation:

just change one (or more) genes to another permitted allele

gene flip:

interchange the values of two genes

gene sequence displacement:

cut a sequence and insert at another position

gene sequence inversion:

revert the order of a (partial) sequence

what-ever-you-like:

do something, be happy...



- The mutation rate should be inversely proportional to the size of the genome.
- For larger populations maybe reduce mutation rate in the on-going optimization process.

# GA: crossover possibilities

simple crossover:

parents	cut	children
(101101)	(10 1101)	→ (100111)
(010111)	(01 0111)	→ (011101)
(2, 8, 98, 3)	(2, 8,  98, 3)	→ (2, 8, 40, 4)
(1, 9, 40, 4)	(1, 9,  40, 4)	→ (1, 9, 98, 3)

k-point crossover:

cut at  $k$  points and interchange the corresponding parts  
(variation: take  $k$  at random)

uniform crossover:

interchange each gene with certain probability

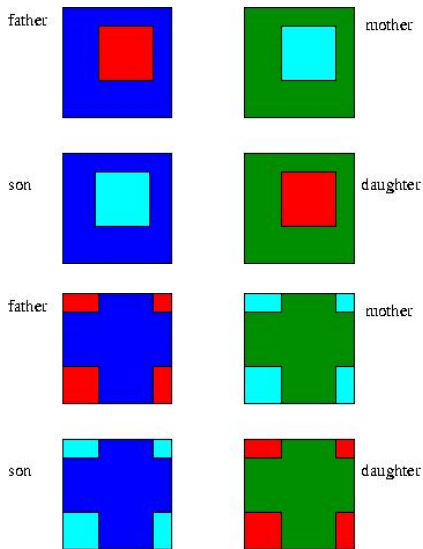
multiple parent mating:

use more than two parents and interchange genes  
(variation: merge entire parent set)

## GA: crossover possibilities (continued)

- arithmetic crossover:** assign to children linear combination of parent genes with some random weight,  $\alpha \in [0, 1]$ , e.g., with  $\alpha = 0.7$  on second gene:  
 $(1.23, 34.5, -2.1) \longrightarrow (1.23, 28.2, -2.1)$   
 $(10.5, 13.5, 23.1) \longrightarrow (1.23, 19.8, 23.1)$   
(again variations: as  $k$ -point, or with all genes, or with  $k$  at random)
- blended crossover:** blend two corresponding parent genes with a certain, usually fixed, value  $\alpha \in [-0.5, \infty]$  according to the current gene spread
- simulated binary crossover:** blend two corresponding parent genes according to a suitable probability density function
- what-ever-you like:** remember, do something, be happy...

# GA: crossover example (2-point cyclic crossover)



- select two grid points
- interchange rectangles

A genetic algorithm can be summarized in the following principal loop:

```
InitializePopulation()      # initialization
EvaluateIndividuals()      # evaluation          DONE
while not Stopping():      # stopping
    DetermineParents()      # selection
    GenerateChildren()      # recombination    DONE
    MutateChildren()        # mutation          DONE
    EvaluateIndividuals()   # evaluation          DONE
    ReestablishPopulation() # selection
```